

Abstract Data Types and Basic Data Structures

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Giving credit where credit is due:

- Most of slides for this lecture are based on slides created by Dr. Ben Choi, Louisiana Technical University.
- I have modified them and added new slides

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Abstract Data Type

Abstract Data Type

- *Data Structure* declaration
 - *Operations* performed on the data structure
 - e.g., create, destroy, or manipulate
 - These are logical operations that are independent of the actual implementation!
- Provides *data encapsulation* (information hiding)
- An ADT is implemented as a Class in languages such as C++ and Java
- Algorithms can be designed, specified, and proven correct using the logical properties of ADTs
- Performance analysis depends on the implementation!

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ADT Specification

- The specification of an ADT describes how the operations (functions, procedures, or methods) behave in terms of Inputs and Outputs
- A specification of an operation consists of:
 - Calling prototype
 - Preconditions
 - Postconditions
- The calling prototype includes
 - name of the operation
 - parameters and their types
 - return value and its types
- The preconditions are statements
 - assumed to be true when the operation is called.
- The postconditions are statements
 - assumed to be true when the operation returns.

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Operations for ADT

- **Constructors**
 - create a new object and return a reference to it
- **Access functions**
 - return information about an object, but do not modify it
- **Manipulation procedures**
 - modify an object, but do not return information
- **Destructors**
 - deallocate an object

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More on ADTs

- **State of an object**
 - current value of its data
- Some books claim that constructors and manipulation procedures should be described in terms of Access functions
 - Maybe...
- **Recursive ADT**
 - if any of its access functions returns the same class as the ADT

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ADT Design for Lists

`IntList nil` //constant denoting the empty list.

`IntList constructList(int newElement, IntList oldList)`

Precondition: None.

Postconditions: If `newList = constructList(newElement, oldList)`

- then
1. `newList` refers to a newly created list object;
 2. `newList` \neq `nil`;
 3. `first(newList) = newElement`;
 4. `rest(newList) = oldList`

`IntList rest(IntList aList)` // access fcn

`int first(IntList aList)` // access function Precondition: `aList` \neq `nil`

Precondition: `aList` \neq `nil`

Postcondition: if `element = first(aList)` then

1. `element` \neq `nil`

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Binary Tree

Q A binary tree T is a set of elements, called nodes, that is empty or satisfies:

1. There is a distinguished node r called the root
2. The remaining nodes are divided into two disjoint subsets, L and R , each of which is a binary tree.
 - L is called the left subtree of T and R is called the right subtree of T .

Q There are at most 2^d nodes at depth d of a binary tree.

Q A binary tree with n nodes has height at least $\lceil \lg(n+1) \rceil - 1$.

Q A binary tree with height h has at most $2^{h+1} - 1$ nodes

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Binary Tree Example

Q What node is the root?

Q What is the depth of each node?

- How many nodes are there at that depth?
- Is this the maximum number of nodes at that depth?

Q How many internal nodes?

Q How many leaves?

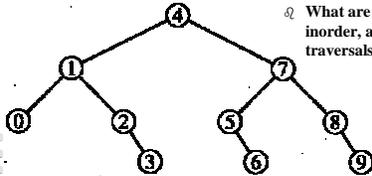
Q What is the value of n ?

Q What is the height of the tree?

Q What is the minimum (maximum) height of a binary tree with this many nodes?

Q What is the height of each subtree?

Q What are the preorder, inorder, and postorder traversals?



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Stacks

Q A stack is a linear structure in which insertions and deletions are always made at one end, called the top.

Q This updating policy is called last in, first out (LIFO).

Q Operations:

- `Stack create()`
- `boolean isEmpty(Stack s)`
- `Object top(Stack s)`,
- `void push(Stack s, Object e)`,
- `void pop(Stack s)`

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Queue

Q A queue is a linear structure in which

- all insertions are done at one end, called the rear or back, and
- all deletions are done at the other end, called the front.

Q This updating policy is called first in, first out (FIFO).

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Priority Queue

Q A priority queue is similar to a FIFO queue but different...

- element order is related to each element's priority, rather than its chronological arrival time.

Q "As each element is inserted into a priority queue, *conceptually* it is inserted *in order of its priority*."

Q The one element that can be inspected and removed is the *most important element* currently in the priority queue.

- a cost viewpoint: the smallest priority
- a profit viewpoint: the largest priority

Q Priority queue operations are not in $\Theta(1)$. Their complexity varies depending on the implementation, as we shall see.

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Set: first some basics...

- ∅ A set is a collection of distinct elements.
- ∅ The elements are of the same “type”
- ∅ “element e is a member of set S ” is denoted as $e \in S$
- ∅ Read “ e is in S ”
- ∅ A particular set is defined by listing or describing its elements between a pair of curly braces:
 $S_1 = \{a, b, c\}$, $S_2 = \{x \mid x \text{ is an integer power of } 2\}$
read “the set of all elements x such that x is ...”
- ∅ $S_3 = \{\} = \emptyset$, has no elements, called empty set
- ∅ A set has no inherent order.

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Subset, Superset; Intersection, Union

- ∅ If all elements of one set, S_1 , are also in another set, S_2 ,
- ∅ Then S_1 is said to be a *subset* of S_2 , $S_1 \subseteq S_2$ and S_2 is said to be a *superset* of S_1 , $S_2 \supseteq S_1$.
- ∅ Empty set is a subset of every set, $\emptyset \subseteq S$
- ∅ *Intersection*
 $S \cap T = \{x \mid x \in S \text{ and } x \in T\}$
- ∅ *Union*
 $S \cup T = \{x \mid x \in S \text{ or } x \in T\}$

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Sequence

- ∅ A group of elements in a *specified order* is called a sequence.
- ∅ A sequence can have repeated elements.
- ∅ Sequences are defined by listing or describing their elements in order, enclosed in parentheses.
 - e.g. $S_1 = (a, b, c)$, $S_2 = (b, c, a)$, $S_3 = (a, a, b, c)$
- ∅ A sequence is *finite* if there is an integer n such that the elements of the sequence can be placed in a one-to-one correspondence with $\{1, 2, 3, \dots, n\}$.
- ∅ If all the elements of a finite sequence are distinct, that sequence is said to be a *permutation* of the finite set consisting of the same elements.
- ∅ One set of n elements has $n!$ distinct permutations.

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Cardinality

- ∅ A set, S , is *finite* if there is an integer n such that the elements of S can be placed in a one-to-one correspondence with $\{1, 2, 3, \dots, n\}$
 - in this case we write $|S| = n$
- ∅ How many distinct subsets does a finite set on n elements have?
 - There are 2^n subsets.
- ∅ How many distinct subsets of cardinality k does a finite set of n elements have?
 - There are $C(n, k) = n!/((n-k)!k!)$, “ n choose k ”

$$\binom{n}{k}$$

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Tuples and Cross Product

- ∅ A *tuple* is a finite sequence.
 - Ordered pair (x, y) , triple (x, y, z) , quadruple, and quintuple
 - A k -tuple is a tuple of k elements.
- ∅ The *cross product* of two sets, say S and T , is $S \times T = \{(x, y) \mid x \in S, y \in T\}$
- ∅ $|S \times T| = |S| |T|$
- ∅ It often happens that S and T are the same set,
 - e.g. $N \times N$
where N denotes the set of natural numbers, $\{0, 1, 2, \dots\}$

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Relations and Functions

- ∅ A *relation* is some subset of a (possibly iterated) cross product.
- ∅ A *binary relation* is some subset of a simple cross product, e.g. $R \subseteq S \times T$
 - The “less than” relation can be defined as $\{(x, y) \mid x \in N, y \in N, x < y\}$
- ∅ Important properties of relations; let $R \subseteq S \times S$
 - reflexive: for all $x \in S$, $(x, x) \in R$.
 - symmetric: if $(x, y) \in R$, then $(y, x) \in R$.
 - antisymmetric: if $(x, y) \in R$, then $(y, x) \notin R$
 - transitive: if $(x, y) \in R$ and $(y, z) \in R$, then $(x, z) \in R$.
- ∅ A relation that is reflexive, symmetric, and transitive is called an *equivalence relation*,
 - I.e., partitions the underlying set S into equivalence classes S_1, S_2, \dots s.t. elements within S_i are equivalent to each other.
- ∅ A *function* is a relation in which no element of S (of $S \times T$) is repeated with the relation. (informal def.)

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Union-Find ADT for Disjoint Sets

- Q Through a *Union* operation, two (disjoint) sets can be combined.
 - (to insure the disjoint property of all existing sets, the original two sets are removed and the new set is added)
 - Let the set ids of the original two sets be, s and t , $s \neq t$
 - Then, the new set has a unique set id that is neither s nor t .
- Q Through a *Find* operation, the current *set id* of an element can be retrieved.
- Q Often elements are integers and the set id is some particular element in the set, called the leader, as in the example in the book

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Union-Find ADT Example

Notice how this ADT differs from the book!

- Q **unionFind create(int n)**
 - // create a set of n singleton disjoint sets $\{\{1\},\{2\},\{3\},\dots,\{n\}\}$
- Q **setId find(UnionFind sets, int element)**
 - // return the set id for *element*
- Q **void makeSet(unionFind sets, int element)**
 - //union one singleton set $\{e\}$ (e not already in the sets) // into exiting sets
- Q **void union(unionFind sets, setId s, setId t)**
 - // $s \neq t$
 - // a new set is created by union of set $\{s\}$ and set $\{t\}$
 - // the new set id is either s or t , in some cases $\min(s, t)$

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Dictionary ADT

- Q A dictionary is a general associative storage structure.
- Q Items in a dictionary
 - have an identifier, and
 - associated information that needs to be stored and retrieved.
- Q No order is implied for identifiers in a dictionary ADT
- Q The Dictionary ADT is useful in dynamic programming, which is covered later in the semester.

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