

CSCE 451/851

Operating Systems Principles

Memory Management Basics

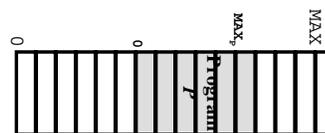
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<http://www.cse.unl.edu/~goddard/Courses/CSCE451>

1

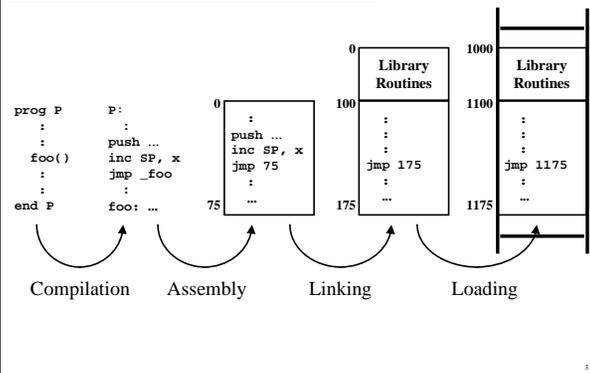
Memory Layout Address spaces

- ◆ Memory — a linear array of bytes
 - » *Physical address space* — that supported by the hardware
 - ◆ starting at address 0, going to address MAX
 - » *Logical address space* — a process's view of memory
 - ◆ starting at address 0, going to address MAX_p
- ◆ But where do addresses come from?
`MOV r0, 0xffffa620e`



Address Generation

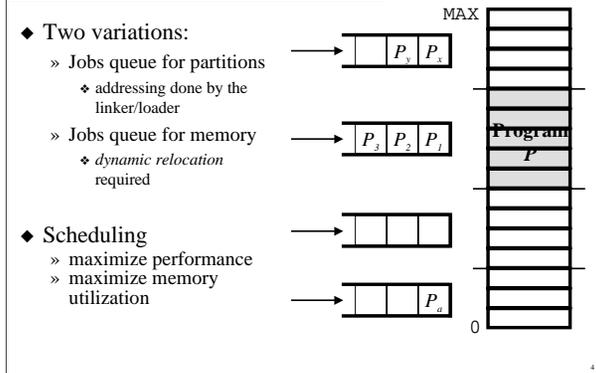
The compilation pipeline



3

Simple Memory Management Schemes

Fixed-sized partitions

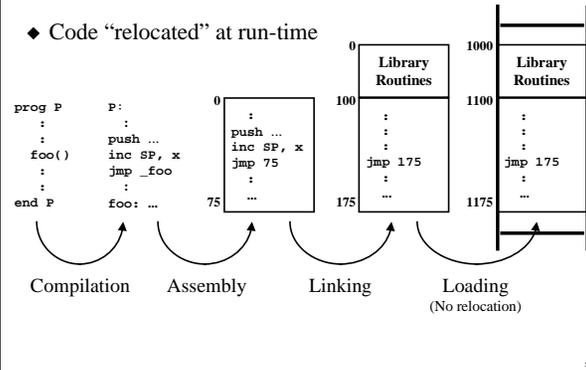


4

Dynamic Program Relocation

Program compilation

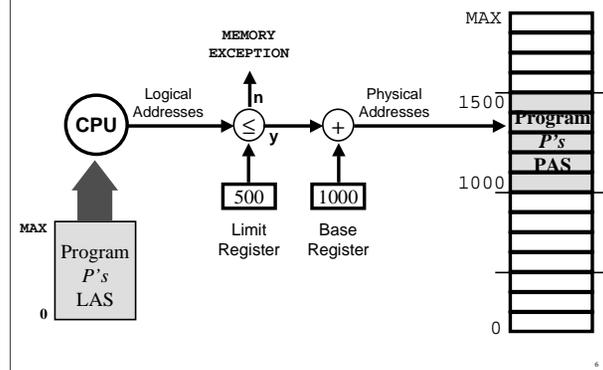
◆ Code “relocated” at run-time



5

Dynamic Program Relocation

Base + Limit registers

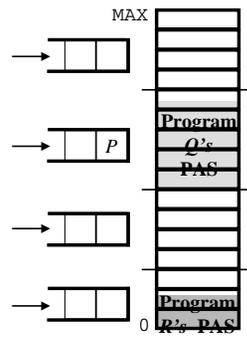


6

Memory Management Issues

Fragmentation

- ◆ Internal fragmentation
- ◆ External fragmentation

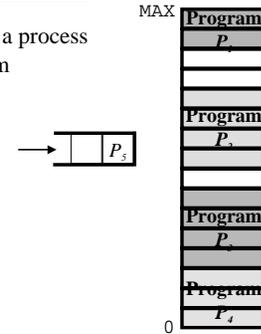


7

Simple Memory Management Schemes

Variable-sized partitions

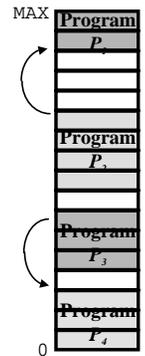
- ◆ Allocate a partition when a process is admitted into the system
- ◆ Keep track of...
 - » full-blocks
 - » empty-blocks (holes)
- ◆ Allocation strategies
 - » first-fit
 - » best-fit
 - » worst-fit



8

Variable-Sized Partitions Eliminating Fragmentation

- ◆ **Compaction**
 - » relocate programs to coalesce holes
- ◆ **Swapping**
 - » preempt processes & reclaim their memory



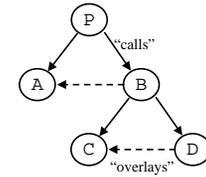
9

Executing programs larger than physical memory Overlays

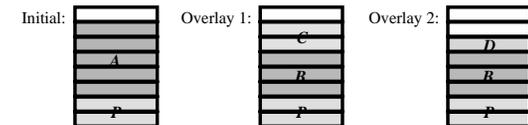
- ◆ **Program call graph**

```

prog P      func A()   func B()
:          :          :
:          :          :
A()        :          C()
B()        end A      D()
:          :          :
end P      :          end B
    
```



- ◆ **Memory layout**



10